

Stochastic Cycles in VAR Processes

Massimo Franchi and Paolo Paruolo

MF: Università di Roma "La Sapienza"

PP: Joint Research Centre of the EC & Università dell'Insubria

Second International Conference in Memory of Carlo Giannini
Banca d'Italia, 19-20 January 2010.

Main contributions of this paper

1. This paper presents an **additive decomposition** of the **MA** representation of VAR processes into **cyclical** components, associated with the **characteristic roots** of the VAR polynomial.
2. It is a **Beveridge-Nelson** type of **decomposition** in which the **contribution** of each root to the **dynamics** of the process is explicit. All the coefficients of the **MAD** representation are **characterized** in terms of the VAR coefficients.
3. **Relations** with **structural time series** models, see e.g. Harvey (1990), and with **common features** literature, see e.g. Engle and Kozicki (JBES, 1993), are discussed.

VAR representation and characteristic roots

Consider a

$$\text{VAR: } X_t + \Pi_1 X_{t-1} + \cdots + \Pi_{d_\Pi} X_{t-d_\Pi} = \epsilon_t;$$

let

$$\Pi(z) := \sum_{n=0}^{d_\Pi} \Pi_n z^n, \quad z \in \mathbb{C}, \quad \Pi_n \in \mathbb{R}^{p \times p}, \quad \Pi_0 = I,$$

and

$$\det \Pi(z) = \prod_{u=1}^q (1 - w_u z)^{a_u}, \quad a_u > 0,$$

where $z_u := 1/w_u$ is a characteristic root and q is the total number of roots; then

$$\text{adj } \Pi(z) =: G(z) \prod_{u=1}^q (1 - w_u z)^{b_u}, \quad 0 \leq b_u < a_u, \quad G(z_u) \neq 0.$$

Inverse function and poles

Hence

$$C(z) := \text{inv } \Pi(z) = \frac{\text{adj } \Pi(z)}{\det \Pi(z)} = \frac{G(z)}{\prod_{u=1}^q (1 - w_u z)^{m_u}}, \quad G(z_u) \neq 0,$$

where $m_u := a_u - b_u > 0$ is the order of the pole of $\text{inv } \Pi(z)$ at z_u .

MA and BN

The **complex** roots come in **conjugate pairs**; let

$$w_u =: \rho_u e^{i\lambda_u}, \quad 0 \leq \lambda_u < 2\pi,$$

and index

a **complex pair** by $u : 0 < \lambda_u < \pi$

and

a **real root** by $u : \lambda_u \in \{0, \pi\}$.

Moving Average Decomposition representation

Theorem

The *MAD* representation of X_t is

$$X_t = \sum_{u: 0 < \lambda_u < \pi} A_u(L) c_u(L) \epsilon_t + \sum_{u: \lambda_u \in \{0, \pi\}} B_u(L) d_u(L) \epsilon_t + R(L) \epsilon_t,$$

where

$$M(L) := \sum_{n=0}^{d_M} M_n L^n, \quad M_n \in \mathbb{R}^{p \times p}, \quad M = A_u, B_u, R,$$

is a *matrix polynomial* of *finite degree* d_M and

$$s(L) := \sum_{n=0}^{d_s} s_n L^n, \quad s_n \in \mathbb{R}, \quad s = c_u, d_u,$$

is a *scalar polynomial* of degree d_s .

Theorem ctd

Moreover,

$$\det B_u(0) = 0$$

and $A_u(L)$, $B_u(L)$, $R(L)$ have finite degree

$$d_{A_u} = 2m_u - 1, \quad d_{B_u} = m_u - 1, \quad d_R = d_G - d_g,$$

where m_u is the order of the pole of $\text{inv } \Pi(z)$ at z_u and

$$d_s = \infty \quad \iff \quad |z_u| > 1, \quad s = c_u, d_u.$$

1. $I(1)$ and cointegration $z_1 = 1, m_1 = 1$, see Engle and Granger (ECTA, 1987), Stock and Watson (JASA, 1988).
2. $I(2)$ and cointegration $z_1 = 1, m_1 = 2$: Johansen (ET, 1992).
3. Non stationary seasonal roots $z_u = \pm 1, z_u = \pm i, m_u = 1$: Hylleberg, Engle, Granger, and Yoo (JoE, 1990), Cubadda (JAE, 1999), Johansen and Schaumburg (JoE, 1999).
4. Co-dependence $z_u = \infty, m_u \geq d_{\Pi}$: Gourioux and Paucelle (WP, 1988), Vahid and Engle (JAE, 1993), Vahid and Engle (JoE, 1997), Franchi and Paruolo (WP, 2009).

Example from Benati and Surico (AER, 2009)

Let $X_t = (r_t, \pi_t, y_t)'$ and consider

$$\text{VAR: } X_t = A_1 X_{t-1} + A_2 X_{t-2} + \epsilon_t$$

where A_1, A_2 ; because

$$g(z) = c_z(z-1.24)(z-1.57)(z-2.18)(z-2.38)(z-2.95)(z-20.95),$$

each z_u is **real** and **stable**, $m_u = 1$ and $d_{B_u} = 0$. Moreover, because

$$d_R = d_G - d_g = 2 - 6 < 0,$$

the finite MA part $R(L)\epsilon_t$ is **absent** from the **MAD**.

Hence one has

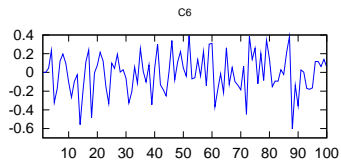
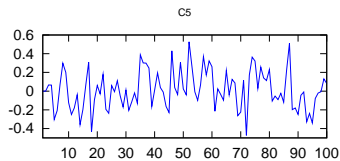
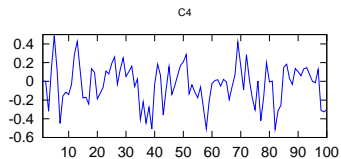
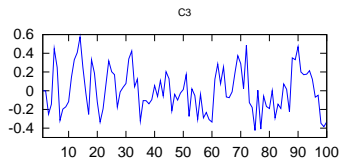
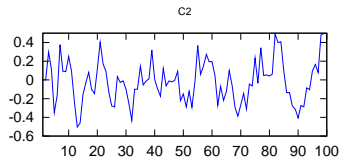
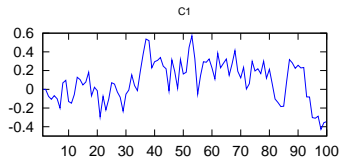
$$\text{MAD: } X_t = \sum_{u=1}^6 B_u d_u(L) \epsilon_t, \quad B_u = \gamma_u \delta'_u, \quad d_u(z) = \sum_{n=0}^{\infty} \left(\frac{1}{z_u} \right)^n z^n,$$

for γ_u, δ_u of dimension 3×1 [Go](#); that is,

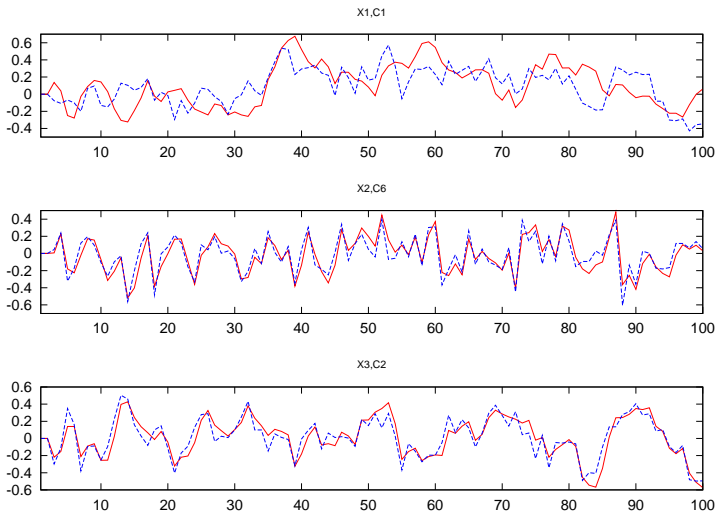
$$X_t = \sum_{u=1}^6 \begin{matrix} \gamma_u \\ (3 \times 1) \end{matrix} \begin{matrix} c_{u,t} \\ (1 \times 1) \end{matrix},$$

and we call $c_{u,t} := d_u(L) \delta'_u \epsilon_t$ the u^{th} **stochastic cycle** in X_t .

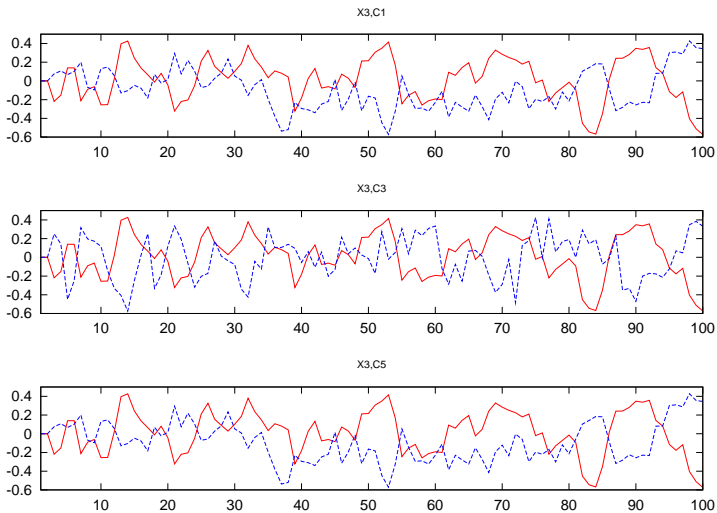
Stochastic cycles in X_t



Concordance between $X_{j,t}$ (red line) and $C_{u,t}$



Concordance between $X_{3,t}$ (red line) and $c_{u,t}$ ctd



Consider another **example**

$$\text{VAR: } X_t = \begin{pmatrix} -1 & -4/3 \\ 2 & 5/3 \end{pmatrix} X_{t-1} + \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} X_{t-2} + \epsilon_t$$

with

$$g(z) = -\frac{1}{3}(2z - 3);$$

hence $z_1 = 3/2$, $m = 1$ and $d_B = 0$. Moreover, because

$$d_R = d_G - d_g = 2 - 1 = 1,$$

the finite MA part $R_0\epsilon_t + R_1\epsilon_{t-1}$ is **present** in the MAD.

Hence one has

$$\text{MAD: } X_t = B d(L)\epsilon_t + R_0\epsilon_t + R_1\epsilon_{t-1}, \quad d(L) = \sum_{n=0}^{\infty} \left(\frac{2}{3}\right)^n L^n,$$

$$B = \frac{1}{8} \begin{pmatrix} -7 \\ 11 \end{pmatrix} (3 : 1) =: \gamma\delta';$$

that is, one has the **factor** structure

$$X_t = \begin{matrix} \gamma \\ (2 \times 1) \end{matrix} \begin{matrix} c_t \\ (1 \times 1) \end{matrix} + R_0\epsilon_t + R_1\epsilon_{t-1},$$

where $c_t := d(L)\delta'\epsilon_t$ is the only **stochastic cycle** in X_t .

A **natural** choice of

$$A: \quad u_t = A\epsilon_t, \quad \text{Var}(u_t) = I,$$

is

$$A = \begin{pmatrix} (\delta' \Omega \delta)^{-1/2} \delta' \\ (\delta'_{\perp} \Omega^{-1} \delta_{\perp})^{-1/2} \delta'_{\perp} \Omega^{-1} \end{pmatrix}, \quad \text{Var}(\epsilon_t) = \Omega.$$

This implies

$$c_t = d(L) \delta' \epsilon_t = d(L) \delta' A^{-1} u_t = d(L) (\delta' \Omega \delta)^{1/2} u_{1,t}$$

so that $u_{1,t}$ is the **business cycle** shock and $u_{2,t}$ is the **idiosyncratic** shock.

Conclusions and work in progress

1. **MAD** includes many different representations as particular cases;
2. Its coefficients are **explicit, non recursive** functions of the VAR coefficients;
3. **Inference** in a likelihood based framework;
4. **VARMA** processes.

Dedicatory and thanks



If $|z_u| > 1$, then the expansion of $C(z)$ around 0 defines the

$$\text{MA: } X_t = \sum_{n=0}^{\infty} C_n \epsilon_{t-n}, \quad C_n \in \mathbb{R}^{p \times p}, \quad C_0 = I;$$

if $z_u = 1$ or $|z_u| > 1$, then the expansion of $C(z)$ around 1 defines the

$$\text{BN: } X_t = C(1) \sum_{n=0}^t \epsilon_{t-n} + (1-L) \sum_{n=0}^{\infty} C_n^* \epsilon_{t-n} + \text{in. values.}$$

A_1, A_2 matrices

$$A_1 = \begin{pmatrix} 1.21 & 0.01 & 0.14 \\ -0.03 & 0.47 & 0.07 \\ -0.11 & -0.05 & 1.02 \end{pmatrix}, A_2 = \begin{pmatrix} -0.32 & -0.01 & -0.05 \\ 0.02 & -0.02 & -0.02 \\ 0.08 & 0.00 & -0.23 \end{pmatrix}.$$

◀ Back

$$B_1 = \begin{pmatrix} 1 \\ -0.03 \\ -0.13 \end{pmatrix} (1.78 : -0.27 : 1.87)$$

$$B_2 = \begin{pmatrix} 1 \\ -0.22 \\ -1.18 \end{pmatrix} (0.61 : 0.69 : -2.76)$$

$$B_3 = \begin{pmatrix} 1 \\ -1.44 \\ -2.28 \end{pmatrix} (-0.51 : -0.71 : 0.58)$$

◀ Back

$$B_4 = \begin{pmatrix} 1 \\ 0.7 \\ -0.87 \end{pmatrix} (-0.97 : 0.25 : 0.28)$$

$$B_5 = \begin{pmatrix} 1 \\ 1.8 \\ -14.4 \end{pmatrix} (0.07 : 0.04 : 0.03)$$

$$B_6 = \begin{pmatrix} 1 \\ -31.5 \\ 0.82 \end{pmatrix} \frac{1}{1000} (0.16 : 4 : -0.4)$$

◀ Back